

BLTouch : Auto Bed Leveling Sensor for 3D Printers

Smart V3.0 Highlights

Logic Voltage Free : 3.3V / 5V logic voltage free(default)

Long Stroke : The stroke becomes 1.6mm longer than the previous stroke

Smart V2.0 and later versions highlights

Blue & Red LED : Blue and Red LED for checking wiring defects.

Engineering plastic Push-pin : Engineering plastic push-pin can be bent more easily than aluminum pins so that engineering plastic push-pin can be recovered well and the device can be protected.

BLTouch – Smart V3.0				
BLTouch Instruction	Center Of PWM (Available PWM Range ± 20)	G-code		
		Marlin / Duet	Repetier	Smoothieware
Push-pin Down(deploy)	650 us (10°)	M280 Px S10	M340 Px S650	M280 S3.3
Alarm Release & Touch SW Mode(M119)	1165 us (60°)	M280 Px S60	M340 Px S1165	M280 S5.88
Push-pin Up(Stow)	1475 us (90°)	M280 Px S90	M340 Px S1475	M280 S7.43
Self-test	1780 us (120°)	M280 Px S120	M340 Px S1780	M280 S8.99
5V Logic Zmin (option : Only for unusual case)	1985 us (140°)	M280 Px S140	M340 Px S1985	M280 S10.01
Logic voltage Free Zmin (default : open drain)	2090 us (150°)	M280 Px S150	M340 Px S2090	M280 S10.53
Alarm Release & Push-pin UP	2190 us (160°)	M280 Px S160	M340 Px S2190	M280 S11.05

※ Depending on your board, you can need to adjust the PWM range or Duty cycle.
 ※ 5V Logic Zmin(140°) for unusual board : H Signal is very weak(Not recommended for general board)

Specification		BLTouch CAD Dimension	
Voltage / Current	4.8 ~ 5.1 V		
Current	15mA		
Maximum(Peak)	300mA		
Z Probe Output	Logic Free (Open Drain : default) or 5V		
Open Drain VDS / ID	Max VDS = 5V / Max ID = 300mA		
PCB / Soldering	OSP / Lead Free		
Cable Length	150±5 mm (for retail)		
Weight	0.35oz (10g)		
Wiring	3Pin : Brown (GND), Red (+5V) Orange (control signal) 2Pin : Black(GND) White (Zmin)		
Case & Push-pin	Polycarbonate (PC)		

※ Additional power supply may be needed in case which your board does not supply enough amperage.

※ Electronic devices can be damaged or even destroyed if connected to the wrong side polarity.

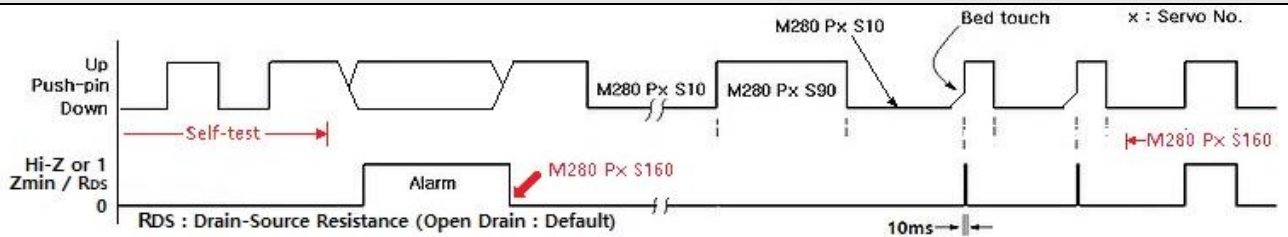
[The wrong terminal connect to 5V(+) and GND(-)]

※ **Set Zmin pull-up on your firmware when using Logic Free (In most cases, it is already set up)**

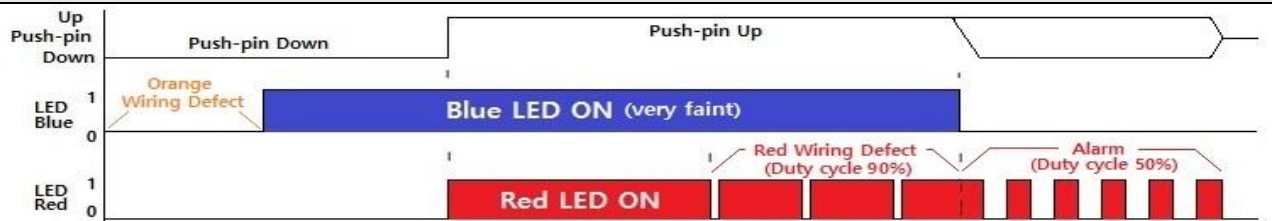
※ Depending on your type of 3D printer, you may need to remove or add some parts of the board.

※ Selling price and specifications are subject to change without prior notice.

Signal Timing Diagram



Blue & Red LED (Please check wiring defects with Blue and Red LED(Smart V2.0 and later).



※ Red wiring defect : When the BLTouch was disconnected and reconnected during normal operation. Unlike previous versions, it does not perform self-test even if wiring defects occur during printing.

Wiring : Soldering and firmware update might be needed in rare case



[I can find a servo pin on my board.](#) [↗ click here](#)
RAMPS1.3/1.4, MKS-Gen V1.3, MKS-Base V1.4, etc.



[I can not find any Servo pin on my board.](#) [↗ click here](#)
MKS-Base V1.2, mini-Rambo, etc.



[I can not find Servo Pin on my board and](#) [↗ click here](#)
[#define SERVO0_PIN is not included in pins_YourMotherboard.h.](#)
Sanguinololu1.3a, Melzi , Ender-3, Anet, FlashForge, Azteeg X3, etc.
※ Depending on your type of 3D printer, you may need to remove or add some parts of the board.

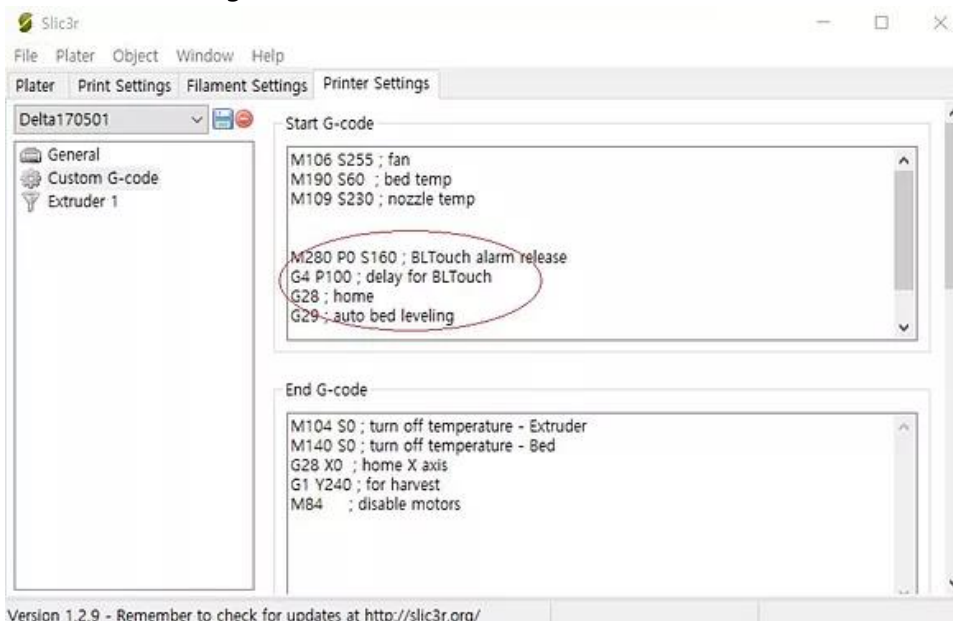


[32bit board](#) [↗ click here](#)
Smoothieboard, MKS-Sbase, BBP1S, Alligator, AZSMZ, STEVAL-3DP001V1, Duet, etc.



e.g. Slic3r

Insert the following G-code into Slic3r or Cura



■ Setting (e.g. Marlin firmware)

Please refer to other auto bed leveling setting documents (Youtube or G+ , etc.).

Troubleshooting : <https://igg.me/at/BLTouch-C/ts/11834379>

Marlin-bugfix-2.0.x Setting

<https://github.com/MarlinFirmware/Marlin/archive/bugfix-2.0.x.zip>

Step 1 : Copy the file below and overwrite at the Marlin folder. <== e.g. default

Marlin-bugfix-2.0.x\config\default\Configuration.h

Marlin-bugfix-2.0.x\config\default\Configuration_adv.h

Step 2 : Look at the Configuration.h at your previous firmware and edit Configuration.h at Marlin.

Step 3 : Check your 3D printer works well.

Step 4 : Please install your BLTouch.

Step 5 : Edit Configuration.h and Configuration_adv.h like below.

■ Configuration.h

```
//===== Endstop Settings =====
#define USE_ZMIN_PLUG // a Z probe
#define ENDSTOPPULLUPS // BLTouch Smart V3.0 and Later
#define ENDSTOP_INTERRUPTS_FEATURE

//===== Z Probe Options =====
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN
#define BLTOUCH
#if ENABLED(BLTOUCH)
  #define BLTOUCH_V3
  #if ENABLED(BLTOUCH_V3)
    // #define BLTOUCH_FORCE_5V_MODE //for 5V logic
    #define BLTOUCH_FORCE_OPEN_DRAIN_MODE // default : Logic Voltage Free
  #endif
#endif

#define PROBING_HEATERS_OFF // *option
#define PROBING_FANS_OFF // *option
#define X_PROBE_OFFSET_FROM_EXTRUDER 0 //Depend on your BLTouch installation value
#define Y_PROBE_OFFSET_FROM_EXTRUDER -22 //Depend on your BLTouch installation value
#define Z_PROBE_OFFSET_FROM_EXTRUDER -2.35 //Depend on your BLTouch installation value
#define MIN_PROBE_EDGE 20
#define Z_CLEARANCE_DEPLOY_PROBE 15 // set up at least 15
#define Z_CLEARANCE_BETWEEN_PROBES 10 // set up at least 10

//===== Bed Leveling =====
// Choose a line of below lines and remove // at the start of the line
// #define AUTO_BED_LEVELING_3POINT
// #define AUTO_BED_LEVELING_LINEAR
#define AUTO_BED_LEVELING_BILINEAR
// #define AUTO_BED_LEVELING_UBL
// #define MESH_BED_LEVELING

//===== Extra Features =====
#define NUM_SERVOS 3 // set up at least 1
#define SERVO_DELAY { 300, 300, 300 }
```

Marlin 1.1.x(1.1.9) Setting

<https://github.com/MarlinFirmware/Marlin/archive/1.1.x.zip>

- Step 1 : Copy the file below and overwrite at the Marlin folder. <= e.g. Delta
Marlin\example_configurations\delta\generic\configuration.h
Marlin\example_configurations\delta\generic\configuration_adv.h
- Step 2 : Look at the Configuration.h at your previous firmware and edit Configuration.h at Marlin 1.1.x
- Step 3 : Check your 3D printer works well.
- Step 4 : Please install your BLTouch.
- Step 5 : Edit Configuration.h and Configuration_adv.h like below.

■ Configuration.h

```
//===== Endstop Settings =====
#define USE_ZMIN_PLUG // a Z probe
#define ENDSTOPPULLUPS // BLTouch Smart V3.0 and Later
#define ENDSTOP_INTERRUPTS_FEATURE

//===== Z Probe Options =====
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN
// #define Z_MIN_PROBE_ENDSTOP
// #define FIX_MOUNTED_PROBE
#define BLTOUCH
#if ENABLED(BLTOUCH)
  #define BLTOUCH_DELAY 100 // *option
#endif
#define PROBING_HEATERS_OFF // *option
#define PROBING_FANS_OFF // *option
#define X_PROBE_OFFSET_FROM_EXTRUDER 0 // Depend on your BLTouch installation value
#define Y_PROBE_OFFSET_FROM_EXTRUDER -22 // Depend on your BLTouch installation value
#define Z_PROBE_OFFSET_FROM_EXTRUDER -2.35 // Depend on your BLTouch installation value
#define MIN_PROBE_EDGE 20
// #define Z_PROBE_ALLEN_KEY
#define Z_CLEARANCE_DEPLOY_PROBE 15 // set up at least 15
#define Z_CLEARANCE_BETWEEN_PROBES 10 // set up at least 10

//===== Bed Leveling =====
// Choose a line of below lines and remove // at the start of the line
// #define AUTO_BED_LEVELING_3POINT
// #define AUTO_BED_LEVELING_LINEAR
#define AUTO_BED_LEVELING_BILINEAR
// #define AUTO_BED_LEVELING_UBL
// #define MESH_BED_LEVELING

//===== Additional Features =====
#define EEPROM_SETTINGS // Enable for M500 and M501 command

//===== Extra Features =====
#define NUM_SERVOS 3 // set up at least 1
#define SERVO_DELAY { 300, 300, 300 }
```

Previous Versions before Marlin RC7

■ Configuration.h

```
//===== Mechanical Settings =====
const bool Z_MIN_ENDSTOP_INVERTING = false;

//===== Z Probe Options =====
// #define Z_MIN_PROBE_ENDSTOP // *RC4 ~ RC6
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN // *RC4 ~ RC6

//===== Bed Auto Leveling =====
#define AUTO_BED_LEVELING_FEATURE
#define X_PROBE_OFFSET_FROM_EXTRUDER 20 //Your BLTouch X_PROBE_OFFSET_FROM_EXTRUDE
#define Y_PROBE_OFFSET_FROM_EXTRUDER -20 //Your BLTouch Y_PROBE_OFFSET_FROM_EXTRUDE
#define Z_PROBE_OFFSET_FROM_EXTRUDER -1.0 //Your BLTouch Z_PROBE_OFFSET_FROM_EXTRUDE
#define Z_SAFE_HOMING

//===== R/C SERVO support =====
#define NUM_SERVOS 3
#define SERVO_ENDSTOP_ANGLES {{0,0}, {0,0}, {10,90}} // 10=deploy, 90=retract
// #define DEACTIVATE_SERVOS_AFTER_MOVE
```

If you want more additional information about the other versions, please visit our website, www.antclabs.com